

Routh Stability

Special Case

first column zero

ie $s^3 + 2s^2 + s + 2 = 0$ $\leftarrow$ Char eqn

s^3	1	1
s^2	2	2
s^1	$\frac{(2)(1) - (2)(1)}{2} = 0$	
s^0		

$\Rightarrow$

s^3	1	1
s^2	2	2
s^1	ϵ	
s^0	$\frac{(\epsilon)(2) - (2)(0)}{\epsilon} = 2$	

$\swarrow$

s^3	1	1
s^2	2	2
s^1	0	
s^0	2	

$\Rightarrow$ aux polynomial $2s^2 + 2 = P(s)$
 $\leftarrow$ jw-axis pole(s)

$$P(s) = 2s^2 + 2$$

$$P(s) = 0 = 2s^2 + 2 \Rightarrow s^2 + 1 = 0$$

$$s = \pm j$$

row of zeros

consider $s^5 + 2s^4 + 24s^3 + 48s^2 - 25s - 50 = 0$

s^5	1	24	-25
s^4	2	48	-50
s^3	$\frac{(2)(24) - (1)(48)}{2}$	$\frac{(2)(-25) - (-50)(1)}{2}$	

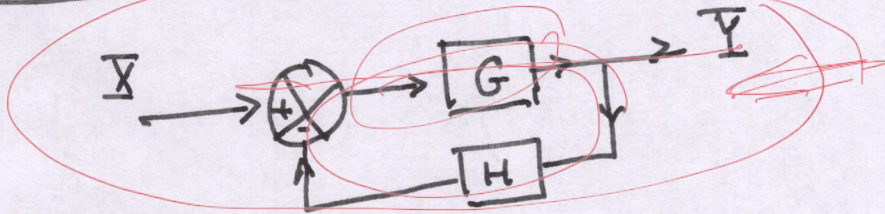
← aux poly P(s)

$$P(s) = 2s^4 + 48s^2 - 50$$

$$\frac{dP(s)}{ds} = 8s^3 + 96s$$

s^5	1	24	-25
s^4	2	48	-50
s^3	8	96	
s^2	$\frac{(8)(48) - (2)(96)}{8}$	$\frac{8(-50) - (2)(0)}{8}$	
s^1	$\frac{(24)(96) - (8)(-50)}{24}$	$\frac{2704}{24} - 50$	
s^0	$\frac{(-50)(2704/24) - (24)(0)}{2704/24}$	-50	

Problem



$$G = \frac{4s+k}{s^2}$$

$$H = \frac{1}{s+2}$$

$$\frac{Y}{X} = \frac{G}{1+GH} \quad \checkmark$$

(a) Find Y/X

(b) Char eqn

(c) Range of k for stable behavior

(d) When is the system marginally stable and the freq of oscillation

soln

$$(a) \frac{\bar{Y}}{\bar{X}} = \frac{G}{1+GH}$$

$$(b) 1+GH = P(s) = 1 + \left(\frac{4s+k}{s^2} \right) \frac{1}{(s+2)}$$

$$P(s) = 0 = s^2(s+2) + 4s + k$$

$$0 = s^3 + 2s^2 + 4s + k$$

(c)

s^3	1	4
s^2	2	k
s	$\frac{(2)(4)-k}{2}$	
s^0	k	

$\Rightarrow$ stable
 $8-k > 0 \Rightarrow 8 > k$
 $\Rightarrow k > 0$

$8 > k > 0$

(d) need zero in 1st column

s^2	1	4
	2	k
	0	

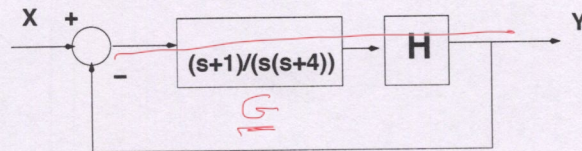
$\Rightarrow P(s) = 2s^2 + k = 0$
 $\Rightarrow k = 8$

$$2s^2 + 8 = 0 \Rightarrow s = \pm j 2$$

$\phi = \frac{2}{2\pi} \text{ Hz}$

Name _____

1. Consider the unity feedback system given by the block diagram below.



a. If $E(s) = X - Y$ evaluate the transfer function $\frac{E}{X}$.

b. Determine $E(s)$ given $x(t) = u(t)$.

c. Determine $H(s)$ such that $e(\infty) = 0.10$.

$$(a) \frac{Y}{X} = \frac{GH}{1 - (-GH)} = \frac{GH}{1 + GH}$$

$$(b) \frac{E}{X} = \frac{X - Y}{X} = 1 - \frac{Y}{X} = 1 - \frac{GH}{1 + GH} = \frac{1 + GH - GH}{1 + GH} = \frac{1}{1 + GH}$$

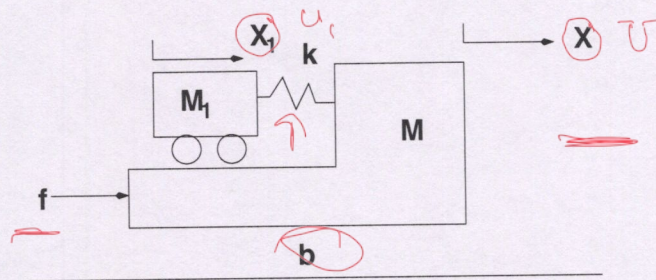
$$\frac{E}{X} = \frac{1}{1 + GH}$$

$$\begin{aligned} x(t) &= u(t) \\ X(s) &= ? \frac{1}{s} \end{aligned}$$

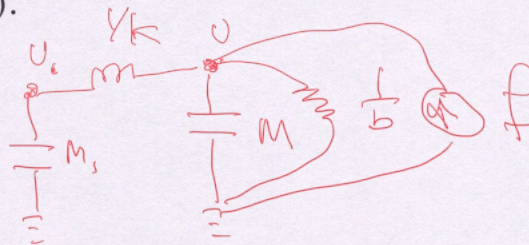
$$E(s) = \left(\frac{1}{s} \right) \left(\frac{1}{1 + GH} \right)$$

$$e(\infty) = \lim_{s \rightarrow 0} s E(s) = 0.10$$

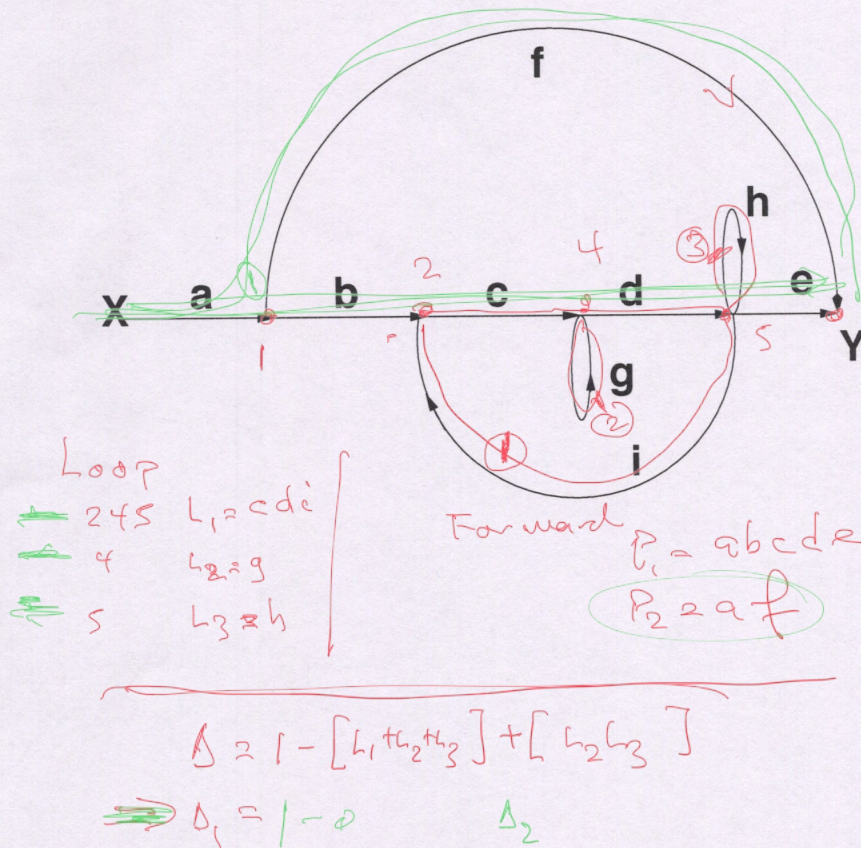
2. Consider the mechanical system where $f(t)$ is the force applied to mass M . The position x and x_1 denote the position of M_1 and M respectively. The variable k is the stiffness of a spring and b is the damper. (note $u = dx/dt$)



- Using the mobility analogy, where force is the through variable and the velocity is the across variable, draw the electromechanical circuit.
- Determine the governing equations of motion in ODE form.
- Evaluate the transfer function of the Laplace transforms of the velocities $U_1(s)/U(s)$.



3. Given the signal flow, determine the transfer function $\frac{Y}{X}$ using Mason's Gain Formula.



4. Consider the unity negative feedback system where the characteristic equation $GH + 1 = 0$.

$$GH = \frac{K(s - 4)}{(s + 1)(s + 2)(s + 3)}$$

- a. Determine the range of values of K where the system is stable.

1.

$$(a) \quad \frac{E}{X} = \frac{1}{1 + H \frac{(s+1)}{s(s+4)}}$$

$$(b) \quad E = \left(\frac{1}{s}\right) \frac{1}{\left[1 + H \frac{(s+1)}{s(s+4)}\right]}$$

$$(c) \quad \lim_{s \rightarrow 0} s E = e(\infty) = \frac{1}{\lim_{s \rightarrow 0} \left(1 + \frac{H}{s} \frac{(1)}{4} + 1\right)} \Rightarrow 0.10$$

$$\boxed{H = ks}$$

$$\frac{1}{1 + k \frac{(1)}{4}} = \frac{1}{10}$$

$$\boxed{k = 40} \quad 36$$

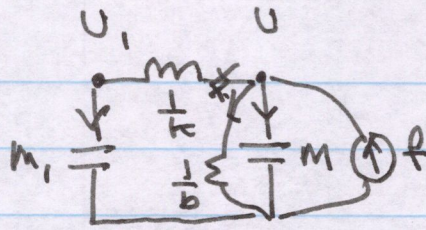
$$(d) \quad 1 + H \frac{(s+1)}{s(s+4)} \Rightarrow 1 + \frac{k(s+1)}{s+4}$$

$$(s+4) + k(s+1) = 0$$

$$(k+1)s + (k+4) = 0 \quad \underline{\text{steady}}$$

2.

(a)



(b)

$$\text{node } U: F = \frac{U}{\frac{1}{ms}} + \frac{U}{b} + \frac{U-U_1}{\frac{s}{k}}$$

node U_1 :

$$\frac{U-U_1}{\frac{s}{k}} = \frac{U_1}{\frac{1}{sm_1}}$$

$$\ddot{f} = \ddot{u} m + b \dot{u} + (u - u_1) k$$

$$(u - u_1) k = m_1 (\ddot{u}_1)$$

$$(c) \left(\frac{U - U_1}{s} \right) \cdot k = s m_1 U_1$$

$$(U - U_1) k = s^2 m_1 U_1$$

$$k U = U_1 [s^2 m_1 + k] \Rightarrow \frac{U_1}{U} = \frac{k}{s^2 m_1 + k}$$

3,

$$P_1 = \sim a b c d e$$

$$P_2 = \sim a f$$

$$L_1 = c d i$$

$$L_2 = g$$

$$L_3 = h$$

$$\Delta = 1 - (L_1 + L_2 + L_3) + (L_2 L_3)$$

$$\Delta_1 = 1 - (0)$$

$$\Delta_2 = 1 - (L_1 + L_2 + L_3) + (L_2 L_3)$$

$$\frac{\overline{Y}}{\overline{X}} = \frac{P_1 \Delta_1}{\Delta} + \frac{P_2 \Delta_2}{\Delta}$$

4

$$GH = \frac{k(s-4)}{(s+1)(s+2)(s+3)}$$

$$1+GH=0 \quad (s+1)(s+2)(s+3)+k(s-4)=0$$

$$s^3 + 6s^2 + (k+11)s + (6-4k) = 0$$

s^3	1	$k+11$	
s^2	6	$6-4k$	
s^1	$\frac{6(k+11)-(6-4k)}{6}$		$\Rightarrow \frac{10k+60}{6}$
s^0	$6-4k$		

$$\frac{6k+66-6+4k}{6} = \frac{60+10k}{6} > 0 \quad \boxed{k > -6} \checkmark$$

$$6-4k > 0 \Rightarrow \boxed{\frac{6}{4} > k}$$

$$\boxed{k < \frac{6}{4}}$$