

Linear Quadratic Regulator (LQR)

problem statement

$$\min \quad PI = \int_0^{\infty} \underline{x}^T Q \underline{x} + \underline{u}^T P \underline{u} \, dt$$

subject to

$$\dot{\underline{x}} = A \underline{x} + B \underline{u}$$

Since $\begin{cases} \infty \rightarrow \\ 0 \rightarrow \end{cases}$ infinite horizon $\Rightarrow$ means $\boxed{\dot{R} = 0}$

The regulator satisfies
the algebraic Riccati eqn

$$RA + A^T R - R \cdot B P^{-1} B^T R + Q = 0$$

$$\underline{u}^0 = -\cancel{\frac{1}{P}} [P^{-1} B R] \underline{x}$$

example 1

① Find A, B, P, Q

$$\dot{x} = -x + u$$

$$PI = \int_0^{\infty} 2x^2 + \frac{u^2}{2} dt$$

$$\left| \begin{array}{cc} A = -1 & B = 1 \\ P = \frac{1}{2} & Q = 2 \end{array} \right| R = r$$

② ~~A. Regn~~ algebra Ricatti eqn

$$r(-1) + (-1)^T r - r(1)\left(\frac{1}{2}\right)^{-1}(1)^T r + (2) = 0$$

$$-r \quad -r \quad -r(1)(2)(1)r + 2 = 0$$

$$\boxed{-2r^2 - 2r + 1 = 0}$$

Soln $r = \begin{cases} (-1) \left[\frac{\sqrt{3}+1}{2} \right] \\ \frac{\sqrt{3}-1}{2} \end{cases} \Rightarrow \text{R is pos def}$

$$\therefore \boxed{r = \frac{\sqrt{3}-1}{2}}$$

③ optimal input

$$u^0 = -\frac{1}{2} [P^{-1} B^T R] x$$

$$u^0 = -\frac{1}{2} \left[\left(\frac{1}{2}\right)^{-1} (1) \left(\frac{\sqrt{3}-1}{2}\right) \right] x$$

$$\boxed{u^0 = -\left(\frac{\sqrt{3}-1}{2}\right) x}$$

④ note $\dot{x} = -x + u^0 \Rightarrow \dot{x} = \left(-1 - \frac{\sqrt{3}}{2} + \frac{1}{2}\right) x \Rightarrow \dot{x} = \left(-\frac{1}{2} - \frac{\sqrt{3}}{2}\right) x$

eigen value
uncontrolled $(-1) \Rightarrow$ controlled $\left(-\frac{1}{2} - \frac{\sqrt{3}}{2}\right)$

Example 2 Find u^0 using HJ-approach

$$\dot{x} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} x + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

$$PI = \int_0^\infty (4x_1^2 + u^2) dt$$

1. Find A, B, Q, P

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad R = \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix}$$

$$P = 1 \quad Q = \begin{bmatrix} 4 & 0 \\ 0 & 0 \end{bmatrix} \leftarrow x^T Q x$$

2. A.R.E.: $RA + A^T R - R B P^{-1} B^T R + Q = 0$

$$\underbrace{\begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_{\begin{bmatrix} 0 & r_1 \\ 0 & r_2 \end{bmatrix}} + \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix}}_{\begin{bmatrix} 0 & 0 \\ r_1 & r_2 \end{bmatrix}} - \underbrace{\begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} 1 \begin{bmatrix} 0 & 1 \end{bmatrix}}_{(1) \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 \end{bmatrix}} \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} + \begin{bmatrix} 4 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 - r_2^2 & r_1 - r_2 r_3 \\ r_1 - r_2 r_3 & 2r_2 - r_3^2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

matrix should be symmetric!!
 $[A] \quad a_{ij} = a_{ji}$

3. Solve for R

$$\begin{aligned} 4 - r_2^2 &= 0 \\ r_1 - r_2 r_3 &= 0 \\ r_1 - r_2 r_3 &= 0 \\ 2r_2 - r_3^2 &= 0 \end{aligned} \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} \text{same} \checkmark$$

$$4 - r_2^2 = 0 \Rightarrow r_2 = \pm 2 \Rightarrow \boxed{r_2 = 2}$$

$$2r_2 - r_3^2 = 0 \Rightarrow 4 - r_3^2 = 0 \Rightarrow r_3 = \pm 2 \Rightarrow \boxed{r_3 = 2}$$

$$r_1 - r_2 r_3 = 0 \Rightarrow r_1 - (2)(2) = 0 \Rightarrow \boxed{r_1 = 4}$$

$$R = \begin{bmatrix} 4 & 2 \\ 2 & 2 \end{bmatrix}$$

4. Optimal input

$$u^0 = -P^{-1} B^T R \underline{x}$$

$$u^0 = -(1)^{-1} \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 4 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$u^0 = - \begin{bmatrix} 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = -2x_1 - 2x_2$$

example 3 Determine the Alg. Ricatti eqn

$$\dot{\underline{x}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & -3 \end{bmatrix} \underline{x} + \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix} \underline{u}; \quad PI = \int_0^{\infty} \underline{x}_1^2 + \underline{x}_2^2 + 4\underline{u}_1^2 + \underline{u}_2^2 dt$$

① Find A, B, P, Q

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & -3 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix} \quad P = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}$$

$$Q = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$P^{-1} = \frac{1}{4} \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix}$$

$$R = \begin{bmatrix} r_{11} & r_{12} & r_{13} \\ r_{21} & r_{22} & r_{23} \\ r_{31} & r_{32} & r_{33} \end{bmatrix} \Rightarrow \text{sym} \quad \begin{bmatrix} r_{11} & r_{12} & r_{13} \\ r_{12} & r_{22} & r_{23} \\ r_{13} & r_{23} & r_{33} \end{bmatrix}$$

② $RA + A^T R - R B P^{-1} B^T R + Q = 0$

$$R \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & -3 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & -2 \\ 0 & 1 & -3 \end{bmatrix} R = R \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix} \left(\frac{1}{4}\right) \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{\begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix} \left(\frac{1}{4}\right) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 4 \end{bmatrix}} R + \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\left(\frac{1}{4}\right) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 1/4 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

example 4

$$\dot{\underline{x}} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \underline{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u \quad \left. \vphantom{\dot{\underline{x}}} \right\} \text{given } \alpha = 1$$

$$PI = \int_0^{\infty} \alpha x_1^2 + \cancel{x_2^2} u^2 dt$$

$$1^{\circ} \quad A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad P = 1 \quad Q = \begin{bmatrix} \alpha & 0 \\ 0 & 0 \end{bmatrix}$$

$$R = \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} \quad P^{-1} = \frac{1}{1}$$

$$2^{\circ} \quad \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} + \begin{bmatrix} 0 & -2 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} \\ - \underbrace{\begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \frac{1}{1} \begin{bmatrix} 0 & 1 \end{bmatrix}}_{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}} \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} + \begin{bmatrix} \alpha & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -r_2^2 - 4r_2 + \alpha & -r_2 r_3 - 2r_3 - 3r_2 + r_1 \\ -r_2 r_3 - 2r_3 - 3r_2 + r_1 & -r_3^2 - 6r_3 + 2r_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

3^o Determine u° for $\alpha = 1$

$$(a) \ r_2^2 + 4r_2 = 1 \Rightarrow \boxed{r_2 = \sqrt{5} - 2}$$

$$(b) \ r_3^2 + 6r_3 = 2r_2 \Rightarrow r_3 = \sqrt{2\sqrt{5} + 5} - 3$$

$$(c) \ -r_2r_3 - 2r_3 - 3r_2 + r_1 = 0 \Rightarrow r_1 = \sqrt{5} \sqrt{2\sqrt{5} + 5} - 6$$

$$u^0 = -\left(\frac{1}{1}\right) \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} r_1 & r_2 \\ r_2 & r_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$