

1. Consider the negative unity gain feedback system where $\bar{Y}(s)$ is the output and $X(s)$ is the input and

$$GH = \frac{K[s^2/10]}{s^2(s+3.6)}$$

- (a) Find \bar{Y}/X
- (b) Determine the real-line root locus of the open-loop gain GH
- (c) Determine the intercepts and asymptotes
- (d) Determine the characteristic equation of the closed-loop system
- (e) Evaluate the break-away points
- (f) Draw the completed root-locus diagram

2. Consider the unity neg. feedback system $GHT = \frac{K(s+4)}{s(s+2)(s+1)}$

- (a) Determine real root locus
- (b) Determine intercepts and asymptotes
- (c) characteristic eqn
- (d) Breakaway pts
- (e) $j\omega$ -axis crossing
- (f) Draw completed root-locus

3. Consider the ^{causal} system with a closed-loop transfer function

$$H(s) = \frac{4}{s^2 + 2s + 4} = \frac{\bar{Y}}{X} \quad \frac{\bar{Y}}{U} \quad \frac{Y}{X}$$

- (a) Given $x(t) = u(t)$ find $y(t)$

(b) If $\dot{x} = [A]x + [B]u \quad * \frac{Y}{U} = \frac{4}{s^2 + 2s + 4}$

$$y = [C]x$$

find A, B, C.